## Direct Numerical Simulation : Local Discretisation Approach

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- \* Numerical simulation of turbulence without any turbulence models
- \* Capture the basic physics of fluids in simple flows
- \* Numerical experiments (unphysical ones can be conceived )
- \* A tool for fundamental research Most accurate results
- \* Computationally intensive
- \* Able to resolve both large and small scales

- \* Identification and study the alteration of coherent structures with buoyancy using DNS.
- \* 80% of TKE in wall bounded turbulence is contained in near walls coherent structures
- \* Reduction of turbulent (friction) drag
- \* Enhancement of turbulent mixing
- \* Enhancement/reduction of heat exchange
- \* Strong applicative interest high potential benefit

- Newtonian Fluid, Incompressible, constant properties , Boussinesq approximation and negligible viscous dissipation
- Governing equations in dimensional form are 3D Navier-Stokes equations expressed in vector form.
- Conservation of Mass : $\nabla \mathbf{.u} = 0$
- Conservation of Momentum  $: \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = \frac{-\nabla p}{\rho_0} + \nu \nabla^2 \mathbf{u} - \frac{1}{\rho_0} \frac{dP}{dx} \hat{\mathbf{i}} + \frac{\Delta \rho}{\rho_0} g \hat{\mathbf{k}}$
- Conservation of Energy:  $\rho C_p \left( \frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T \right) = k \nabla^2 T$

- Scales employed for non-dimensionalisation
- Length :  $\delta$  Channel half height
- Velocity  $u\tau$  friction velocity
- ▶ Pressure  $\rho_o u_\tau^2$
- Time :  $\frac{\delta}{u_{\tau}}$
- ▶  $\theta = \frac{T T_c}{T_h T_c}$ Here  $u_r = \sqrt{\frac{\tau_w}{\delta}}$ , where  $\tau_w$  is wall-shear stress.

• Conservation of Mass  $\nabla . \mathbf{u} = 0$ 

• Conservation of Momentum  $\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla p + \frac{1}{Re_{\tau}} \nabla^2 \mathbf{u} + F \hat{\mathbf{i}} + Ri\theta \hat{\mathbf{k}}$ 

• Conservation of Energy 
$$\frac{\partial \theta}{\partial t} + \mathbf{u} \cdot \nabla \theta = \frac{1}{Re_{\tau}Pr} \nabla^2 \theta$$

- ▶ Reynolds number,  $Re = \frac{u_\tau \delta}{\nu}$  which is the ratio of the inertial forces to viscous forces
- ▶ Richardson number,  $Ri = \frac{g\beta\delta(T_h T_c)}{u_\tau^2}$  which represents the importance of natural relative to the forced convection
- ► Prandtl Number  $Pr = \frac{\nu}{\alpha}$  which is the ratio of viscous diffusion rate to the thermal diffusion rate.

#### Geometry of Computational Domain



Figure: Geometry of physical domain.

#### Stretching Transformation

$$\blacktriangleright z(\xi_k) = 1 - \cos\left(\frac{\pi}{2}\xi_k\right)$$

 $\blacktriangleright \ \frac{\partial z}{\partial \xi} = \frac{\pi}{2} sin(\frac{\pi}{2}\xi_k)$ 

$$\blacktriangleright \quad \frac{\partial^2 z}{\partial \xi^2} = \frac{\pi^2}{4} \cos\left(\frac{\pi}{2}\xi_k\right)$$

- ► Wall- normal first-order derivatives in physical space of any quantity  $\Phi$  can be determined as:  $\frac{\partial \Phi}{\partial z} = \frac{1}{\left(\frac{\partial z}{\partial F}\right)} \frac{\partial \Phi}{\partial \xi}$
- ► The Second-order derivative can be determined using chain rule as:  $\frac{\partial^2 \Phi}{\partial z^2} = \frac{1}{(\frac{\partial z}{\partial \xi})^2} \frac{\partial^2 \Phi}{\partial \xi^2} - \frac{\frac{\partial^2 z}{\partial \xi^2}}{(\frac{\partial z}{\partial \xi})^3}$

### Stretching Transformation (Contd.)



Figure: Stretching mesh in wall normal direction

- ▶ The initial condition is provided from a previous simulation of fully developed turbulent channel flow at  $R_e \tau = 180$
- The presence of a solid boundary in turbulent shear flows, the velocity of the fluid is zero for a stationary solid surface (no-slip) , and is mathematically represented as :

#### Initial and Boundary Conditions (Contd.)

\* No-Slip Condition

The presence of a solid boundary in turbulent shear flows, the velocity of the fluid is zero for a stationary solid surface (no-slip) , and is mathematically represented as :

u = v = 0

\* No-Penetration

The wall is considered impermiable, so the normal velocity at the solid surface must be zero and written as:  $w = 0 \label{eq:weak}$ 

- \* Periodic Boundary Conditions :
- $\blacktriangleright \ \phi(x,y,z,t) = \phi(x+L_x,y,z,t) \text{ and }$
- $\phi(x, y, z, t) = \phi(x, y + L_y, z, t)$ Where  $L_x$  and  $L_y$  are periodic lengths

#### Numerical Scheme

- \* The SMAC algorithm described by Amsden and Harlow (1970), modified by later the work of Cheng and Armfield (1995,IJNMF) is a two-step predictor corrector algorithm with implicit handling of diffusion terms and explicit discretisation of convective terms.
- \* Predictor Step:

$$\bullet \quad \widetilde{u} - \frac{\delta t}{Re_{\tau}} \nabla^2 \widetilde{u} = u^n - \delta t (\nabla p^n + (u^n \cdot \nabla) u^n)$$

\* Corrector Step

• 
$$u^{n+1} - \frac{\delta t}{Re_{\tau}} \nabla^2 \widetilde{u} = u^n - \delta t (\nabla p^{n+1} + (u^n \cdot \nabla) u^n)$$

Subtracting the two, we get

$$\blacktriangleright \ u^{n+1} - \widetilde{u} = -\delta t \{ \nabla (p^{n+1} - p^n) \} = -\delta t \{ \nabla (p^*) \}$$

#### Numerical Scheme (Contd.)

$$\blacktriangleright p^{n+1} = p^n + p^*$$

$$\blacktriangleright \ u^{n+1} = \widetilde{u} - \delta t \{ \nabla p^* \}$$

- Taking divergence, assuming  $\nabla . u^{n+1} = 0$
- ▶ We get Pressure-Poisson Equation (PPE) for correction pressure as:

$$\blacktriangleright \nabla^2 p^* = \frac{\nabla . \widetilde{u}}{\delta t}$$

- At solid walls and at inflow  $\frac{\partial p^*}{\partial n} = 0$
- ▶ At outflow  $p_n^* = 0$ , where *n* is the direction of the local normal

#### Discretisation of Convective Terms

#### \* Treatment of Convective Terms

>  $2^{nd}$ - order central differencing scheme is given as:

$$\bar{U}\frac{\partial u}{\partial z}\mid_{i,j,k}=\bar{U}\frac{u_{i,j,k+1}-u_{i,j,k-1}}{2dz}$$

▶ The 6<sup>th</sup> order central-difference scheme is expressed as:

$$\bar{U} \frac{\partial u}{\partial x} |_{i,j,k} = \underbrace{\bar{U}_{i,j,k} - \underbrace{u_{i-3,j,k} + 9u_{i-2,j,k} - 45u_{i-1,j,k} + 45u_{i+1,j,k} - 9u_{i+2,j,k} + u_{i+3,j,k}}_{60dx}$$

#### Discretisation of Convective Terms (Contd.)

- The 3<sup>rd</sup> order upwind scheme as proposed by Kuwahara(1999) can be expressed as: Ū ∂u/∂x |i,j,k = Ai,j,k + Bi,j,k
  A<sub>i,j,k</sub> = Ū<sub>i,j,k</sub>((-ui+2,j,k+8(ui+1,j,k-ui-1,j,k)+ui-2,j,k)/12dx</sub>)) B<sub>i,j,k</sub> = | Ū<sub>i,j,k</sub> | (ui+2,j,k+8(ui+1,j,k+6ui,j,k-4ui-1,j,k+ui-2,j,k)/4dx</sub>) P<sub>e</sub> = (Re<sub>τ</sub>\*Ū<sub>i,j,k</sub>\*dξ)/Jac(k)
- $\blacktriangleright$  Peclet based hybrid scheme with  $6^{th}$  order CDS for  $Pe \leq 2$
- Kuwahara third-order upwinding for Pe>2

#### Discretisation of Diffusion terms and Pressure terms

Along Homogenous directions

$$\blacktriangleright \quad \frac{\partial^2 u}{\partial x^2} \mid_{i,j,k} = \frac{-u_{i+2,j,k} + 16u_{i+1,j,k} - 30u_{i,j,k} + 16u_{i-1,j,k} - u_{i+2,j,k} + u_{i-2,j,k}}{12(dx)^2}$$

Along Inhomogenous direction

$$\begin{array}{l} \begin{array}{l} \frac{\partial^2 u}{\partial z^2} \mid_{i,j,k} = C_{i,j,k} + D_{i,j,k} \\ \\ \end{array} \\ \begin{array}{l} \bullet \quad C_{i,j,k} = \frac{1}{Jac(k)} \frac{-u_{i,j,k+2} + 16u_{i,j,k+1} - 30u_{i,j,k} + 16u_{i,j,k-1} - u_{i,j,k-2}}{12(d\xi)^2} \\ \\ \\ \bullet \quad D_{i,j,k} = \frac{Jac2(k)}{(Jac(k))^3} \frac{-u_{i,j,k} + 8u_{i,j,k+1} - 8u_{i,j,k-1} + u_{i,j,k-2}}{12d\xi} \end{array} \end{array}$$

# Discretisation of Diffusion terms and Pressure terms (Contd.)

$$\blacktriangleright \quad \frac{\partial p}{\partial z} \mid i, j, k = \frac{p_{i,j,k+1} - p_{i,j,k-1}}{2(Jac(k)) * d\xi}$$

• Here 
$$Jac(k) = \frac{\partial z}{\partial \xi}$$
 and  $Jac2(k) = \frac{\partial^2 z}{\partial \xi^2}$ 

- ► One sided forward differencing (Non Uniform Mesh)  $\left(\frac{\partial u}{\partial x}\right)_{i} = \left(\frac{\Delta x_{i+1} + \Delta x_{i+2}}{\Delta x_{i+2}} - \frac{u_{i+1} - u_{i}}{\Delta x_{i+1}} - \frac{\Delta x_{i+1}}{\Delta x_{i+2}} \frac{u_{i+2} - u_{i}}{\Delta x_{i+1} + \Delta x_{i+2}}\right)$
- ► Central differencing (Non Uniform Mesh)  $(\frac{\partial u}{\partial x})_i = \frac{1}{\Delta x_i + \Delta x_{i+1}} [\frac{\Delta x_i}{\Delta x_{i+1}} (u_{i+1} - u_i) + \frac{\Delta x_{i+1}}{\Delta x_i} (u_i - u_{i+1})]$

$$\blacktriangleright \nabla^2 p^* = \frac{\nabla . \widetilde{u}}{\partial t}$$

• The divergence operator  $\frac{\partial}{\partial x}$  is discretised on cell faces.

Similarly the divergence terms are discretised using the same operator:

• 
$$\left(\frac{\partial u^*}{\partial x}\right) = \left\{\frac{2}{dx_1 + dx_2}\right\} [u^*_{i+\frac{1}{2},j,k} - u^*_{i-\frac{1}{2},j,k}]$$
 where  $dx_1 = x_{i+1} - x_i$  and  $dx_2 = x_i - x_{i-1}$ 

#### Treatment of Pressure- Poisson equation (Contd.)

▶ The correction Pressure-gradient terms are discretised as :

$$\begin{array}{l} \frac{\partial p'}{\partial x} \mid_{i+\frac{1}{2},j,k} = \frac{p'_{i+1,j,k} - p'_{i,j,k}}{dx_1} \\ \frac{\partial p'}{\partial x} \mid_{i-\frac{1}{2},j,k} = \frac{p'_{i,j,k} - p'_{i-1,j,k}}{dx_2} \end{array}$$

- This method of discretisation avoids decoupling between pressure and velocity which leads to spurious pressure oscillations
- Momentum interpolation proposed by Rhie and Chow (1983,AIAA Journal) states :

$$u_{i+\frac{1}{2},j,k}^* = \big(\frac{u_{i+1,j,k}^p + u_{i,j,k}^p}{2}\big) - \delta t \big(\frac{p_{i+1,j,k}^n - p_{i,j,k}^n}{x_{i+1} - x_i}\big)$$

$$u_{i-\frac{1}{2},j,k}^* = (\frac{u_{i,j,k}^p + u_{i-1,j,k}^p}{2}) - \delta t(\frac{p_{i,j,k}^n - p_{i,j,k}^n}{x_i - x_{i-1}})$$

 $\blacktriangleright$  Here  $u^p$  is obtained without using the pressure gradient term as shown below

$$u^p - \frac{\delta t}{Re_{\tau}}(\nabla^2 u^p) = u^n - \delta t\{(u^n \cdot \nabla)u^n\}$$

The PPE can be solved using any iterative solver such as SOR, SIP, CGSTAB, SSOR preconditioned GMRES, multigrid, etc.

#### Solution of Transport Equations

• 
$$u^* - \frac{\delta t}{Re_{\tau}} \nabla^2 u^* = u^n - \delta t (\nabla p^n + (u^n \cdot \nabla) u^n + \tilde{f}^n)$$

$$A_P \phi_P + \sum_l A_l \phi_l = Q_p$$

$$\phi_P^{n+1} = \frac{Q_P - A_S \phi_S^{n+1} - A_W \phi_W^{n+1} - A_N \phi_N^n - A_E \phi_E^n - A_T \phi_T^n}{A_P}, \text{ where } n \text{ is iterative counter}$$

• Here residual 
$$\rho^n = Q - A\phi^n$$

- Iteration error  $\epsilon^n = \phi \phi^n$
- Hence  $A\epsilon^n = \rho^n$

• Convergence criteria 
$$|| \rho^n ||_2 = \sqrt{\frac{\sum_{i=1}^N (\rho^n)_i^2}{N}}$$

- ▶  $\frac{\partial \phi(r,t)}{\partial t} = f(\phi,r,t)$ , With  $f(t_0) = f_0$  as an initial-condition. On integrating the above equation between time  $t_n$  and  $t_n + 1(=t_n + \Delta t)$
- Euler ( First-order )  $\phi^{n+1} \phi^n = \int_{t_n}^{t_n+1} f(\phi, r, t) dt$
- Adam Bashforth (Second-order)  $\phi^{n+1} - \phi^n = \int_{t_n}^{t_n+1} (\frac{3}{2}f^n(\phi, r, t) - \frac{1}{2}f^{n-1}(\phi, r, t))dt$



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